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Time Series Cross-Validation Techniques for determining the order of the Autoregressive models

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Abstract: In the present research paper, we introduced some techniques of cross-validation for time series data. Six different types of time series cross-validation techniques are presented and also discussed various problems in selecting the initial training sample size and the size of training folds. In this paper, all cross-validation techniques, most appropriate techniques for model selection in time series analysis and advantages of the each technique are discussed with empirical study.

Keywords: Time series cross-validation, Prediction error, Order of AR model, Training sample, Test sample.

I. INTRODUCTION

Cross-validation is not only a method of choosing the best model but also a method of measuring accuracy. Since the order of the data is important in time series analysis, crossvalidation might be problematic for time series models [1].

The application of cross validation to the time series data is not straight forward. The main reasons are

- (i). Serial correlation in the data.
- (ii). Non-stationarity of the data.

The most appropriate cross-validation techniques are presented in the paper to determine the order of autoregressive model. These cross-validation techniques are useful for

- a) Determining the order of autoregressive model and also the order of moving average model.
- b) Selecting the best ARMA model among candidate models.
- c) Selecting the best time series model among candidate models.

Consider the simple stationary linear autoregressive model of order 'p'

$$y_t = a_1 y_{t-1} + \dots + a_p y_{t-p} + \varepsilon_t$$

where ε_t are *i.i.d* $N(0, \sigma^2)$

The number 'p' is called the order of the AR model. We need to choose 'p'.

It can be written as $y_t = a'x_t + \varepsilon_t$

Where $a = (a_1, a_2, \dots, a_p)'$ and $x_t = (y_{t-1}, y_{t-2}, \dots, y_{t-p})'$

The autoregressive model of order 'p' fitted to the future data $\{\tilde{y}_t\}_{t=1}^m$ is

 $\tilde{y}_t = \hat{a}' \, \tilde{x}_t + \varepsilon_t \, .$

The process $\{\tilde{y}_t\}_{t=1}^m$ has the same distribution as the sample

data $\{y_t\}_{t=1}^n$ but is independent of it, and

 $\tilde{x}_t = (\tilde{y}_{t-1}, \tilde{y}_{t-2}, \dots, \tilde{y}_{t-p})'$ (Obviously, x_t and \tilde{x}_t do not overlap) [2].

The prediction error measures the predictive ability of the estimated model by

$$PE = E\left\{\tilde{y}_t - \hat{a}'\tilde{x}_t\right\}^2$$

An estimate of PE using cross-validation is obtained on averaging the predictive square errors [3]. The following steps are used for estimate the predictive mean square error by cross-validation model selection procedures [4].

Step-1: Estimate a model based on a training sample. **Step-2:** Forecast of a test sample is obtained by using the

estimated model. It is denoted by \hat{y}_{α} .

Step-3: Calculate the value of the predictive square error $(y_{\alpha} - \hat{y}_{\alpha})^2$.

Here y_{α} is a set of observations of the test sample.

Step-4: Repeat Steps (1), (2) & (3) for each α and obtain

$$\mathbf{P}\mathbf{E} = E\left(y_{\alpha} - \hat{y}_{\alpha}\right)^{2}$$

The candidate models are

$$\mathsf{M}_{1}: y_{t} = a_{1}y_{t-1} + \varepsilon$$

$$\mathsf{M}_{2}: y_{t} = a_{1}y_{t-1} + a_{2}y_{t-2} + \varepsilon_{t}$$

$$\mathbf{M}_{3}: y_{t} = a_{1}y_{t-1} + a_{2}y_{t-2} + a_{3}y_{t-3} + \varepsilon_{1}$$

 $M_{p}: y_{t} = a_{1}y_{t-1} + a_{2}y_{t-2} + a_{3}y_{t-3} + \dots + a_{p}y_{t-p} + \varepsilon_{t}$

The best model or most appropriate autoregressive model of order O^* for given a time series data is

$$\mathsf{M}_{o^*}: y_t = a_1 y_{t-1} + a_2 y_{t-2} + a_3 y_{t-3} + \dots + a_{o^*} y_{t-o^*} + \mathcal{E}_t.$$

Where $O^* \leq p$.

Shao(1993) defines the 'optimal model ' M $_{O^*}$, which possess the smallest expected prediction error of any model {M $_O$; $O = 1, 2, 3, \dots, p$ }. Cross-validation estimates the expected prediction error of a model and cross-validatory model selection proceeds by selecting the model with smallest estimated expected prediction error [5].

The optimal AR order O^* is chosen such that $TSCV(O^*) = \min \{ TSCV(O) / O = 1, 2, 3 \dots p \}$

Here TSCV(O) is the estimate of prediction mean square

error in estimating the model M $_o$ [6].

Best model (i.e., optimal model) or most appropriate model M $_{a^*}$ is selected by the time series cross-validation techniques.

II. TIME SERIES CROSS-VALIDATIONS TECHNIQUES

Six different types of cross-validation techniques introduced to determine the order of autoregressive process.

A. Time Series Cross Validation-1 Technique

In time series cross validation-1 model selection procedure, there is a series of test samples; each test sample contains only one observation. The corresponding training samples consisting of the observations prior to the single observation of the test sample. It means that forecast at a time point is dependent on the past observations.



Figure 1. Time Series Cross Validation-1(TSCV-1)

In the figure-1, sample data $\{y_t\}_{t=1}^n$ is repeatedly split into a training sample (shown in grey colour) and a validation set (i.e., test sample) that contains only one observation (shown in black colour).

Training Samples: $\{y_1, y_2, \dots, y_{i+k-1}\}; i = 1, 2, \dots, n-k$

Test Samples: $\{y_{i+k}\}$; $i = 1, 2, \dots, n-k$ (or) $\{y_{\alpha}\}_{\alpha=k+1}^{n}$ Here k is minimum training sample size to estimate the model.

An estimate of PE using TSCV-1 technique is $PE = \frac{1}{n-k} \sum (y_{\alpha} - \hat{y}_{\alpha})^{2}$

B. Time Series Cross Validation-2 Technique

In time series cross validation-2 model selection procedure, there is a series of test samples; each test sample contains only one observation. The corresponding training samples consisting of a number of observations prior to the single observation of the test sample. The TSCV-2 technique is similar to TSCV-1 technique, but the size of training sample in TSCV-2 technique is constant.

Training Samples: $\{y_i, \dots, y_{i+k-1}\}$; $i = 1, 2, \dots, n-k$

Test Samples:
$$\{y_{i+k}\}$$
; $i = 1, 2, \dots, n-k$ (or) $\{y_{\alpha}\}_{\alpha=k+1}^{n}$

Here k is minimum training sample size to estimate the model and is the size of training sample in each split.

An estimate of PE using TSCV-2 technique is

$$PE = \frac{1}{n-k} \sum (y_{\alpha} - \hat{y}_{\alpha})^2$$

Figure 2. Time Series Cross Validation-2(TSCV-2)

In the figure-2, sample data $\{y_t\}_{t=1}^n$ is repeatedly split into a training sample (shown in grey colour), the size of the training samples are fixed and a validation set (i.e., test sample) that contains only one observation (shown in black colour).

C. Time Series Cross Validation-3 Technique

In time series cross validation-3 model selection procedure, there is a series of test samples; each test sample contains only one observation (i.e., 3-step-ahead data point). In time series analysis, multi-step forecasts are relevant than one-step forecasts. The TSCV-3 technique is a relevant selection procedure than TSCV-1 and TSCV-2 techniques.



Figure 3. Time Series Cross Validation-3(TSCV-3)

In the figure-3, sample data $\{y_t\}_{t=1}^n$ is repeatedly split into a training sample (shown in grey colour) and a validation set (i.e., test sample) that contains only one observation (shown in black colour). The single observation of the test sample is a 3-step-ahead data point.

Training Samples: $\{y_1, \dots, y_{i+k-1}\}$; $i = 1, 2, \dots, n-k-2$ Test Samples: $\{y_{i+k+2}\}$; $i = 1, 2, \dots, n-k-2$ (or) $\{y_{\alpha}\}_{\alpha=k+3,k+5,\dots,n}$ Here k is minimum training sample size to estimate the model. An estimate of PE using TSCV-3 technique is

$$\mathbf{P}\mathbf{E} = \frac{1}{n-k-2} \sum \left(y_{\alpha} - \hat{y}_{\alpha} \right)^2$$

D. Time Series Cross Validation-4 Technique

In time series cross validation-4 model selection procedure, there is a series of test samples or test folds, each test fold contains a set of observations and test fold sizes are equal. The TSCV-4 technique is a good model selection procedure than TSCV-1, TSCV-2 and TSCV-3 techniques. *Assumption:*

- 1. n is multiple of k
- 2. The size of first training fold is same as the size of first test fold.
- 3. Test folds are equal in size. It means that each test sample consists of an equal number of observations in it.



Figure 4. Time Series Cross Validation-4(TSCV-4)

Training Samples (or) Training folds:

$$\{y_1, y_2, \dots, y_{i \times k}\}; i = 1, 2, \dots, \frac{n-k}{k}$$

Test Samples (or) Test folds:

$$\left\{y_{(i\times k)+1},\ldots,y_{(i+1)\times k}\right\}; i=1,2,\ldots,\frac{n-k}{k}$$

Here k is minimum training sample size to estimate the model.

An estimate of PE using TSCV-4 technique is

$$\overline{PE} = \frac{1}{n-k} \left[\sum_{k=1}^{2k} (y_{\alpha} - \hat{y}_{\alpha})^2 + \sum_{2k=1}^{3k} (y_{\alpha} - \hat{y}_{\alpha})^2 + \dots + \sum_{(n-k)=1}^n (y_{\alpha} - \hat{y}_{\alpha})^2 \right]$$
Where

Where

 $\sum_{k=1}^{2k} (y_{\alpha} - \hat{y}_{\alpha})^2$ is a total predictive square error of first test

sample $\{y_{k+1}, \dots, y_{2k}\}$

 $\sum_{2k+1}^{3k} (y_{\alpha} - \hat{y}_{\alpha})^2$ is a total predictive square error of second test

sample $\{y_{2k+1}, \dots, y_{3k}\}$

 $\sum_{(n-k)+1}^{n} (y_{\alpha} - \hat{y}_{\alpha})^{2}$ is a total predictive square error of last test sample $\{y_{(n-k)+1}, \dots, y_{n}\}$

E. Time Series Cross Validation-5 Technique

In time series cross validation-5 model selection procedure, there is a series of test samples or test folds, each test fold contains a set of observations and test fold sizes are equal. The corresponding training samples consisting of the number of observations prior to the test sample. In TSCV-5 model selection procedure, the size of training samples and test samples are equal in each split. *Assumption:*

- 1. n is multiple of k
- 2. The size of training fold is same as the size of test fold in each split.
- 3. Test folds are equal in size. It means that each test sample consists of an equal number of observations in it.



Figure 5. Time Series Cross Validation-5(TSCV-5)

Training Samples (or) Training folds:

$$\left\{y_{1+(i-1)k},\dots,y_{i\times k}\right\}; i=1,2,\dots,\frac{n-k}{k}$$

$$\left\{y_{(i\times k)+1}, \cdots, y_{(i+1)\times k}\right\}; i = 1, 2, \cdots, \frac{n-k}{k}$$

Here k is minimum training sample size to estimate the model.

An estimate of PE using TSCV-5 technique is

$$\overrightarrow{PE} = \frac{1}{2} \left[\sum_{k=1}^{2k} (y_{k} - \hat{y}_{k})^{2} + \sum_{k=1}^{3k} (y_{k} - \hat{y}_{k})^{2} + \dots + \sum_{k=1}^{n} (y$$

$$\mathbf{E} = \frac{1}{n-k} \left[\sum_{k=1}^{\infty} (y_{\alpha} - \hat{y}_{\alpha})^2 + \sum_{2k=1}^{\infty} (y_{\alpha} - \hat{y}_{\alpha})^2 + \dots + \sum_{(n-k)+1}^{n} (y_{\alpha} - \hat{y}_{\alpha})^2 \right]$$

Where

$$\sum_{k=1}^{2k} (y_{\alpha} - \hat{y}_{\alpha})^2$$
 is a total predictive square error of first test

sample $\{y_{k+1}, \dots, y_{2k}\}$

 $\sum_{2k+1}^{3k} (y_{\alpha} - \hat{y}_{\alpha})^2$ is a total predictive square error of second test sample $\{y_{2k+1}, \dots, y_{3k}\}$

 $\sum_{(n-k)+1}^{n} (y_{\alpha} - \hat{y}_{\alpha})^{2}$ is a total predictive square error of last test sample $\{y_{(n-k)+1}, \dots, y_{n}\}$

F. Time Series Cross Validation-6Technique

In time series cross validation-6 model selection procedure, there is a series of test samples or test folds, each test fold contains a set of observations which are k-step-ahead data points and test fold sizes are equal. *Assumption:*

- 1. n is multiple of k
- The size of first training fold is same as the size of first test fold.

3. Test folds are equal in size. It means that each test sample consists of an equal number of observations in it.



Figure 6. Time Series Cross Validation-6(TSCV-6)

Training Samples (or) Training folds:

$$\{y_1, \dots, y_{i \times k}\}; i = 1, 2, \dots, \frac{n-2k}{k}$$

Test Samples (or) Test folds:

$$\left\{y_{(i+1)k+1}, \dots, y_{(i+2)k}\right\}; i = 1, 2, \dots, \frac{n-2k}{k}$$

Here k is minimum training sample size to estimate the model.

An estimate of PE using TSCV-6 technique is

$$\mathbf{PE} = \frac{1}{n-2k} \left[\sum_{2k+1}^{3k} (y_{\alpha} - \hat{y}_{\alpha})^2 + \sum_{3k+1}^{4k} (y_{\alpha} - \hat{y}_{\alpha})^2 + \dots + \sum_{(n-k)+1}^n (y_{\alpha} - \hat{y}_{\alpha})^2 \right]$$

Where

 $\sum_{2k+1}^{5k} (y_{\alpha} - \hat{y}_{\alpha})^2$ is a total predictive square error of first test sample $\{y_{2k+1}, \dots, y_{3k}\}$

 $\sum_{3k+1}^{4k} (y_{\alpha} - \hat{y}_{\alpha})^2 \text{ is a total predictive square error of second test}$ sample $\{y_{3k+1}, \dots, y_{4k}\}$

 $\sum_{(n-k)+1}^{n} (y_{\alpha} - \hat{y}_{\alpha})^{2}$ is a total predictive square error of last test sample $\{y_{(n-k)+1}, \dots, y_{n}\}$

III. EMPIRICAL STUDY

We generated a series of 250 observations from the autoregressive model of order 2,

 $y_t = 0.58 y_{t-1} - 0.65 y_{t-2} + \varepsilon_t$, where ε_t are *i.i.d* N(0,1).

The candidate models are

TSCV techniques are used to estimate the optimal order of autoregressive model.

The prediction mean square error for each candidate model is estimated by different TSCV techniques using R Software and these values are presented in table I to V.

Table I. Estimates of PE by TSCV-1 technique

k	Estimates of PE by TSCV-1 technique for the Model				
	AR(1)	AR(2)	AR(3)	AR(4)	AR(5)
25	1.530311	0.973941	0.985433	1.014555	1.025889
50	1.582546	1.01608	1.02759	1.049468	1.059643
75	1.581222	1.00519	1.012122	1.034494	1.038942
100	1.423709	0.986364	0.992325	1.003767	1.007592
125	1.405905	0.993532	0.998706	1.012341	1.014716
150	1.33519	0.941361	0.946084	0.949703	0.951085
175	1.243363	0.934801	0.942493	0.94613	0.944047
200	1.595412	1.136492	1.145097	1.150882	1.146659
225	1.309337	0.770816	0.770429	0.769918	0.781212

For k=225, AR(4) model is the most appropriate model by TSCV-1 technique. Since the estimate of prediction error based on less number of observations, the TSCV-1 technique is not selecting the most appropriate model. The minimum number of observations required to estimate the prediction error is 40 in this situation. For remaining k values, TSCV-1 technique performs well.

Table II.	Estimates	of PE by	TSCV-2	technique
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k	Estimates of PE by TSCV-2 technique for the Model				
	AR(1)	AR(2)	AR(3)	AR(4)	AR(5)
25	1.59852	1.086066	1.163132	1.254259	1.32851
50	1.604598	1.052419	1.081964	1.095242	1.130196
75	1.594136	1.024215	1.041528	1.052716	1.070726
100	1.428297	0.998333	1.006905	1.016553	1.024421
125	1.405954	1.000571	1.009877	1.021016	1.027763
150	1.337799	0.958747	0.964872	0.969574	0.972083
175	1.24323	0.9398	0.94585	0.95669	0.960398
200	1.599547	1.144698	1.162594	1.176925	1.176468
225	1.309116	0.764238	0.766044	0.781315	0.793078

In the TSCV-2 technique, the first observation in each training sample is not far from the observation of the test sample. A minimum number of observations in each training sample are not less than 10 % of the data is considered for the present study. For all selected values of k, TSCV-2 technique performing well.

Table III. Estimates of PE by TSCV-3 technique

k	Estimates of PE by TSCV-3 technique for the Model				
	AR(1)	AR(2)	AR(3)	AR(4)	AR(5)
25	1.779215	1.371621	1.384179	1.399293	1.415454
50	1.835528	1.427255	1.436383	1.462076	1.474493
75	1.84689	1.438611	1.44419	1.471097	1.475356
100	1.63721	1.392555	1.395461	1.407555	1.408046
125	1.599433	1.334273	1.337071	1.349015	1.347026
150	1.451404	1.271021	1.272582	1.27731	1.274207
175	1.461919	1.237995	1.242911	1.251946	1.24351
200	1.647454	1.354596	1.35926	1.368044	1.354306
225	1.596424	1.185301	1.180439	1.176958	1.191044

The TSCV-3 technique is dependent on the observations of the test sample which is h-step ahead data point and the value of k. To select the most appropriate model, we chose h as 2, 3, 4 and 5. The TSCV-3 technique is performing well for the size of training sample which lies between 10% and 75% of the data. For the k (25 to 175) values, TSCV-3 technique performs well.

k	Estimates of PE by TSCV-4 technique for the Model				
	AR(1)	AR(2)	AR(3)	AR(4)	AR(5)
5	1.491581	0.944388	0.958796	1.006564	1.014591
10	1.508478	0.970101	1.025693	1.021178	1.028944
25	1.514073	0.946957	0.951758	0.964936	0.971821
50	1.561074	1.012016	1.023154	1.056757	1.06298
125	1.406476	0.953078	0.953496	0.971115	0.970077

Table IV. Estimates of PE by TSCV-4 technique

In the TSCV-4 technique, we chose the k value such that n-k

 $\frac{n-k}{k}$ is an integer and $k \ge 5$. For all selected values of k,

TSCV-4 technique performs well.

For k=125, the training fold consisting of the first 50% of the data and the test fold consisting of the last 50% of the data.

Table V. Estimates of PE by TSCV-5 technique

k	Estimates of PE by TSCV-5 technique for the Model				
	AR(1)	AR(2)	AR(3)	AR(4)	AR(5)
10	1.538369	1.02339	1.221861	1.19563	1.288271
25	1.522967	0.980885	0.995129	1.027841	1.134396
50	1.56086	1.010527	1.047324	1.071945	1.091911
125	1.406476	0.953078	0.953496	0.971115	0.970077

In the TSCV-5 technique, we chose the k value such that $\frac{n-k}{k}$ is an integer and $k \ge 5$. For all selected values of k,

TSCV-5 technique performing well.

For k=125, the training fold consisting of the first 50% of the data and the test fold consisting of the last 50% of the data.

k	Estimates of PE by TSCV-6 technique for the Model					
	AR(1)	AR(2)	AR(3)	AR(4)	AR(5)	
5	1.496793	0.950885	1.01355	1.212872	1.216627	
10	1.524203	0.982224	0.999622	1.013216	1.017292	
25	1.565564	0.995341	1.003848	1.03383	1.043173	
50	1.407914	0.989371	0.987399	1.035232	1.039462	

Table VI. Estimates of PE by TSCV-6 technique

In the TSCV-6 technique, we chose the k value such that $\frac{n-2k}{k}$ is an integer and $k \ge 5$. The TSCV-6 technique

performs better for small values of k.

By the TSCV techniques, AR(2) model is the most appropriate model for the simulated data.

IV. CONCLUSIONS

In the present research work, we have investigated the use of time series cross-validation techniques for determining the order of autoregressive model. These time series crossvalidation techniques are also useful for obtaining best model among the candidate models in time series forecasting. These time series cross-validation techniques are alternative to the model selection procedures such as Final Prediction Error (FPE) Criterion, Akaike Information Criterion (AIC), Bias-Corrected Akaike Information Criterion (AICc), Bayesian Information Criterion (BIC) and Minimum Description Length (MDL).

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